

The M3S-based electric wheelchair for the people with disabilities

陳適卿

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摘要

Abstract

PURPOSE: This study aims to establish an electronic wheelchair system in Taiwan that conforms to multiple master-multiple slave (M3S) standards. The proposed system could enhance the safety and convenience of people with disabilities. **MATERIAL AND METHOD:** The M3S-based head-controlled electric wheelchair consists of three parts: (A) the input device, (B) the output device, and (C) the safety device. Head movement can be used as the input control to cause the tilting device to produce a corresponding level of analog voltage (backward & forward/left & right) which is then transmitted to the analog/digital conversion module to control the output device (wheelchair's motor). Ten subjects with C5 incompleting spinal cord injury were recruited in the clinical assessment. They were randomly assigned into groups A and B. In the group A, the subjects were assigned to operate the head-controlled wheelchair system with M3S standard before operating the head-controlled wheelchair system without M3S standard. In the group B, the subjects were assigned to operate the head-controlled wheelchair system without M3S standard before operating the head-controlled wheelchair system with M3S standard. Two subjects in the group B drop off due to their personal reasons. **RESULTS:** The time cost for group A in completing tasks 1, 2, and 3 with the M3S and without the M3S were insignificant ($p>0.05$). The time cost for completing in group B was insignificant ($p>0.05$). Thus, the wheelchair operating time is depended on the proficiency of the subjects, not the M3S standard added. **DISCUSSIONS AND CONCLUSIONS:** The time cost for subjects to operate the wheelchair was determined by their proficiency, not the M3S standard control added to the system. However, the M3S-based system did realize the safety mechanism and complex auxiliary tools with and without the plug-in and play function.